Heterogeneous Initial Stress For Spontaneous Rupture Models: The 2011 Tohoku and 2008 Wenchuan Earthquakes

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Outline

- Overview on initial stress setup for dynamic models
- EQdyna: Slip-weakening friction in an elastic or elastoplastic model
- The 2011 M9 Tohoku earthquake: roles of a possible seamount?
- The 2008 M8 Wenchuan earthquake: stress rotations?
- Concluding remarks

Overview on Initial Stress Setup

Ingredients of Spontaneous Rupture Models

• Given lab constraints on friction law and geological/geophysical constraints on geologic structure, Initial stress is the least-constrained ingredient: most important & most flexible?



Practice in Specifying Initial Stress

- Constant, depth-independent stress drop: elastic, strike-slip & dip-slip faulting
- Uniform regional stress field: elastic/plastic, strike-slip faulting, e.g., Rice's group work,...
- Depth-dependent initial stress: elastic/plastic, strike-slip & dip-slip faulting, e.g., Andrews et al. (2007), Ma and Andrews (2010),...
- Heterogeneous initial stress: e.g., Day (1982), Andrews & Barall (2011), ...

Heterogeneous Initial Stress

- Andrews and Barall (2011): random & self-similar (power-law) stress drop, long-wavelength stress variation, GM prediction
- Earthquake-cycle simulation: heterogeneous stress evolves over multi-cycles
 - Lapusta group's work
 - Duan & Oglesby (2005, 2006, 2007)
- Depth-dependent, nonuniform initial stress:
 - Subducted seamounts in 2011 Tohoku EQ?
 - Stress rotations in 2008 Wenchuan EQ?



Brief Overview

An Explicit FEM Method

- For rupture dynamics and seismic wave propagation
 - One of the codes in the SCEC validation exercise
 - Benefit a lot from our code validation exercise: Thanks to
 Ruth and All
- Slip-weakening friction mainly:
 - rate-state friction in process
- TSN of Day et al. (2005)

$$\tilde{T}_{\nu} = \frac{\Delta t^{-1} M^{+} M^{-} \left[\left(\dot{u}_{\nu}^{+} - \dot{u}_{\nu}^{-} \right) + \Delta t^{-1} \left(u_{\nu}^{+} - u_{\nu}^{-} \right) \delta_{\nu n} \right] + M^{-} R_{\nu}^{+} - M^{+} R_{\nu}^{-}}{a (M^{+} + M^{-})} + T_{\nu}^{0}, \quad \nu = s, d, n,$$
(4)

$$\rho u_{i,tt} = \sigma_{ij,j} + f_i$$

Hybird MPI/OpenMP Parallelization

- For spontaneous rupture modeling of recent large earthquakes: large fault dimension at reasonable element sizes
- Ground motion prediction with dynamic source characterization: high frequency
- Run on large cluster systems: EOS at TAMU, Lonestar & Kraken via NSF

MPI, level

Parallelism

OpenMP level Parallelism

Process 2



A Simulation Example

- Parallel computing: a Hybrid MPI/OpenMP approach on multicore supercomputers
 - 500 m element size on ~440kmx220km fault
 - 200 seconds dynamic simulation
 - ~580 million elements
 - ~35 hr wallclock time, ~640 GB memory using 256 cores for production runs on EOS at TAMU

The 2011 M9 Tohoku EQ

Roles of a Possible Seamount?

Some Kinematic Inversion Results: Slip



Some Kinematic Results: Rupture



No up-dip rupture before ~40-45 seconds!

Shao et al

Features & Questions

- Large Shallow Slip: 2 competing views
 - max near hypocenter: v-strengthening & stable sliding near trench?
 - max near trench: v-weakening & strain accumulation?
- Rupture propagation
 - No up-dip rupture before ~40-45 seconds: why?
 - Seafloor rupture ~60-75 seconds: strain release (+ stress drop) or passive slip (- stress drop)?
 - Deeper rupture ~90 seconds: what drives?

What Can Stall Up-Dip Rupture

- Low shear stress vs. High frictional strength
- Non-Planar fault geometry vs. Subducted seafloor features (e.g., Seamounts)





Subducted Seamounts?



3D Spontaneous Rupture Models

- Geology Structure:

 Fault: a 10° dipping thrust fault
 Velocity structure: 1D

 Friction Law on Fault: Slipweakening, +/- stress drops mimic V-weakening/strengthening
- Initial Stress: depth-dependent normal stress, pore pressure; nominal μ_0 for initial shear.





A Procedure of Specifying Initial Stress

• Pure thrust faulting: max and min principal effective stresses are relevant.

$$\sigma_3 = (1 - \lambda)g \int_0^z \rho(z')dz',$$

$$\sigma_1 = R\sigma_3,$$

 $R = [\sin(2\beta) + \mu_0(1 + \cos(2\beta))] / [\sin(2\beta) - \mu_0(1 - \cos(2\beta))].$

$$\sigma_n = \sigma_1 \sin^2 \beta + \sigma_3 \cos^2 \beta,$$

$$\tau_0 = (\sigma_1 - \sigma_3) \sin\beta \cos\beta.$$

Physical Parameters on the Fault: a Preferred Dynamic Rupture Model

- Pore pressure: λ =pore pressure/lithostatic
- Friction coefficients: static μs /dynamic μd
- Nominal friction for initial shear stress: μο



Initial Stresses on the Fault



Dynamic Rupture Propagation

A movie of slip velocity and accumulated slip from the preferred model: see preferMod.wmv

Quantities on Fault From the Model



Reproduce Epicenter Seafloor Displacements

Station	Horizontal Displacement (m)		Vertical Displacement (m)	
	Observed	Simulated	Observed	Simulated
MYGI	24	23.8	3	2.5
MYGW	15	15.0	-0.8	-0.7
KAMS	23	20.0	1.5	5.2
KAMN	15	15.1	1.6	4.3
FUKU	5	5.5	0.9	-1.3



Importance of the Seamount

 Without other changes, just a longer/stronger seamount: much smaller event



A movie of slip velocity and accumulated slip: see refMod.wmv



Conclusions on the Tohoku EQ

- The 2011 Mw 9.0 Tohoku-Oki earthquake may be primarily controlled by failure of a ~70 km long by 25 km wide subducted seamount.
 - Located just up-dip of the hypocenter
 - Stalled up-dip rupture: a barrier at beginning
 - Produced max slip ~50 m w/ max stress drop of ~50 MPa finally: an asperity
- Large slip near trench may be confined to a small area just up-dip of the seamount
 - Velocity-weakening (strain accumulation) near trench is not required
 - How strong velocity-strengthening (how large negative stress drop) affects the amplitude of slip there
- Parallel computing facilitates exploration of physics of megathrust earthquakes: more dynamic models needed.

The 2008 Wenchuan EQ

Stress Rotations?

Field Observations: Surface Rupture

- Two faults ruptured: ~12 km apart on surface
 - Incomplete slip partitioning: oblique on Beichuan fault, thrust on Pengguan fault. Why?
 - Dynamic branching: how and why?





Kinematic Inversions of Seismic & Geodetic Data

- Complex spatial-temporal evolution of rupture
 - First 16 seconds on Pengguan only
 - Triggered rupture on Beichuan at ~20 s and ~40 km away

Shao et al., 2010, 2011, 2012

Our Branched Fault Model

- Two smoothly curved faults: 12 km apart surface, merge at 10 km depth
- Material properties: homogeneous half-space w/ typical crustal rocks
- Friction law: time-weakening (essentially slip-weakening w/ varying D₀)
- Initial stress: depth-dependent effective stress
 - stress orientations by α : the angle between σ_1 and fault strike (focus of this study)



Setup of initial stresses in the models: as simple as possible

(1) σ_3 is vertical: lithostatic less pore pressure. (2) σ_1 and σ_2 are horizontal. (3) $\sigma_2 = \sigma_3$. (4) $\sigma_1 = R\sigma_3$, R>1. (5) σ_1 makes an angle of α with the fault strike.



Uniform Regional Stress Fields

Cannot produce incomplete slip partitioning
Cannot produce dynamic branching

Different α for Two Faults

- Dynamic branching occurs with incomplete slip partitioning.
- But, the triggering feature reported by kinematic inversions is not produced

Preferred Model: Stress Rotations

- Incomplete slip partitioning
- Dynamic branching by triggering as reported in inversions

Conclusions on the Wenchuan EQ

- Uniform regional stress orientation along the fault system cannot produce incomplete slip partitioning and dynamic branching features observed in the event.
- Stress rotations between the two faults and along strike of the faults are needed to produce the two features.
 - Evidence: shear-wave splitting

Concluding Remarks

Heterogeneous Initial Stress for Dynamic Rupture Models

Initial Stress & Dynamic Models

- With observations of recent large earthquakes, dynamic models may allow us to infer initial stress conditions.
- Procedures for specifying initial (principal) stresses that account for depth-dependence & heterogeneities are needed in the dynamic rupture community.