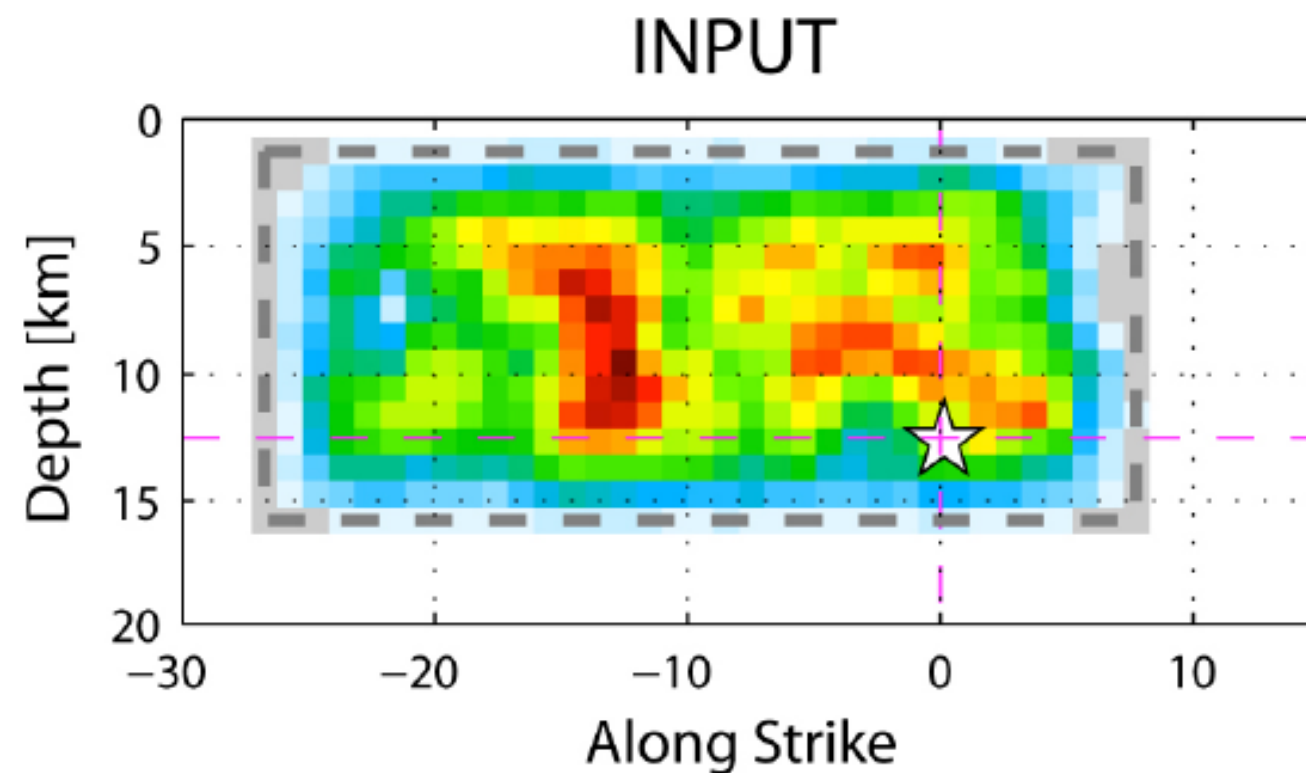


Source Inversion Validation (SIV)

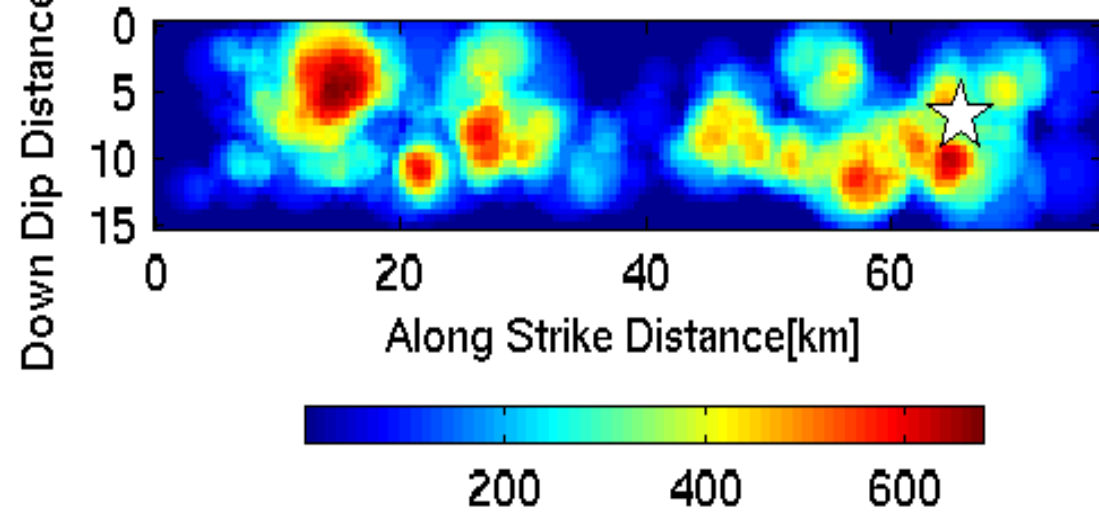
Past, Present, and Future



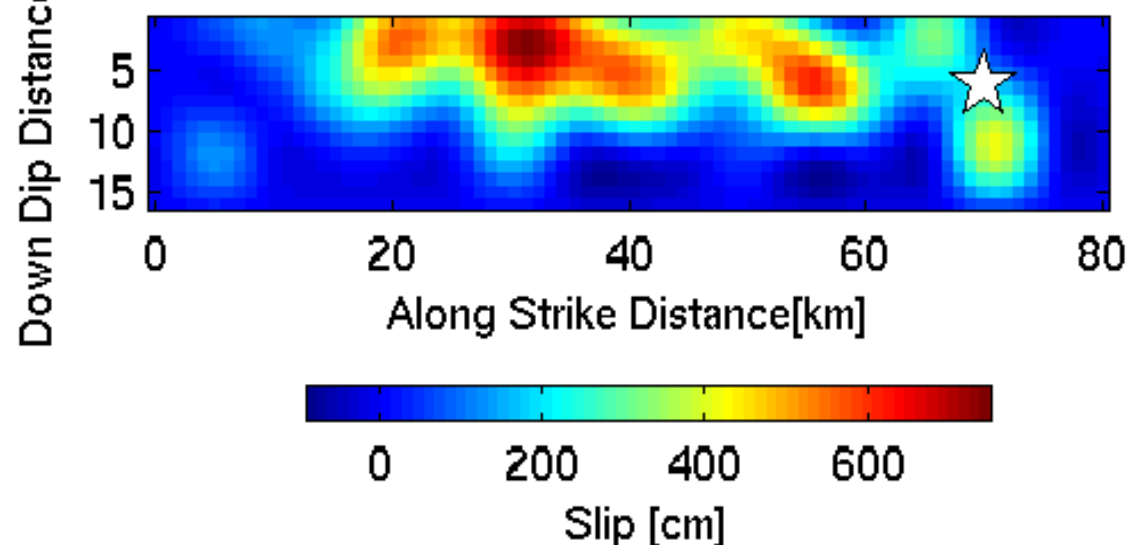
Morgan Page
Martin Mai
Danijel Schorlemmer

Different inversion methods,
model parameterizations,
constraint choices, and data
sets lead to different results.

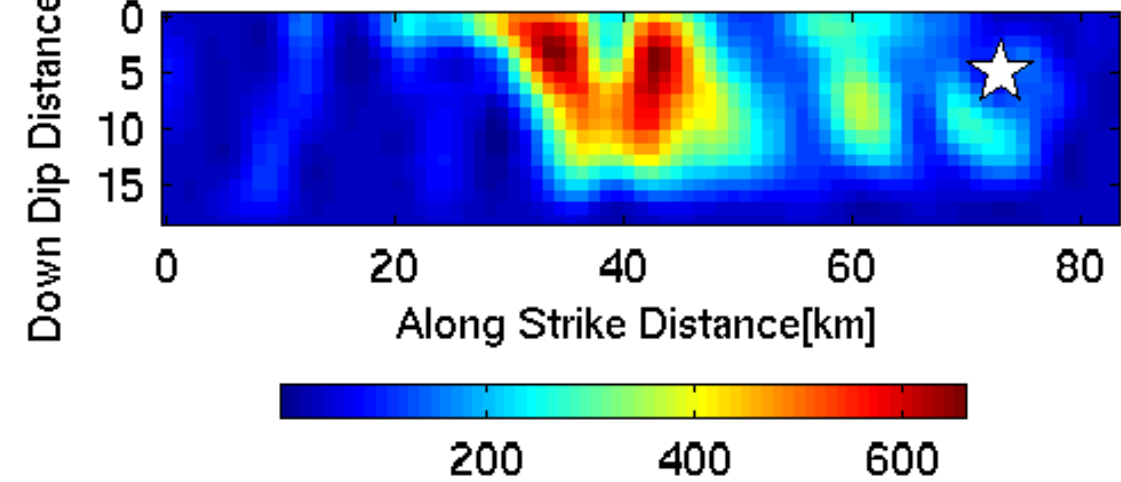
Landers (1992) - Zeng & Anderson, Mw = 7.20
[evID: 29.5; evNO: 42]



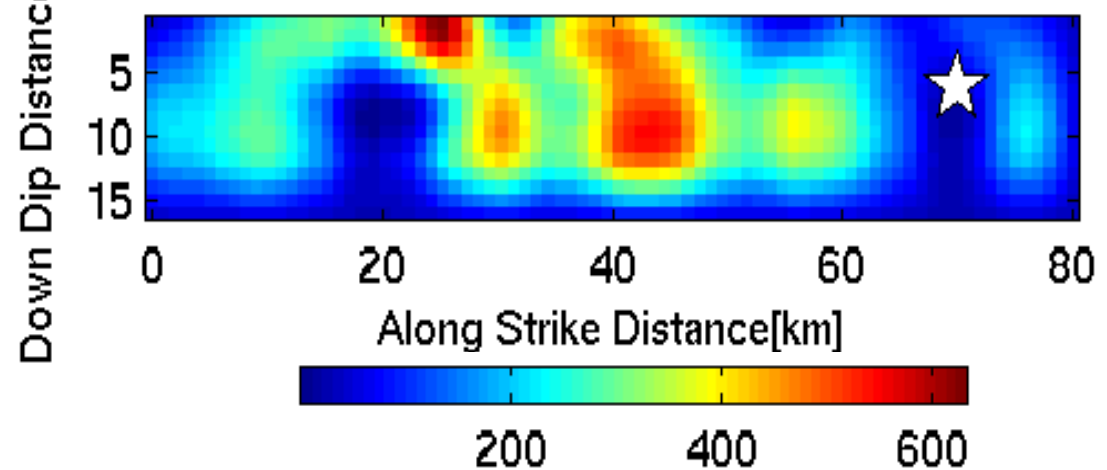
Landers (1992) - Hernandez et al, Mw = 7.31
[evID: 29.3; evNO: 40]



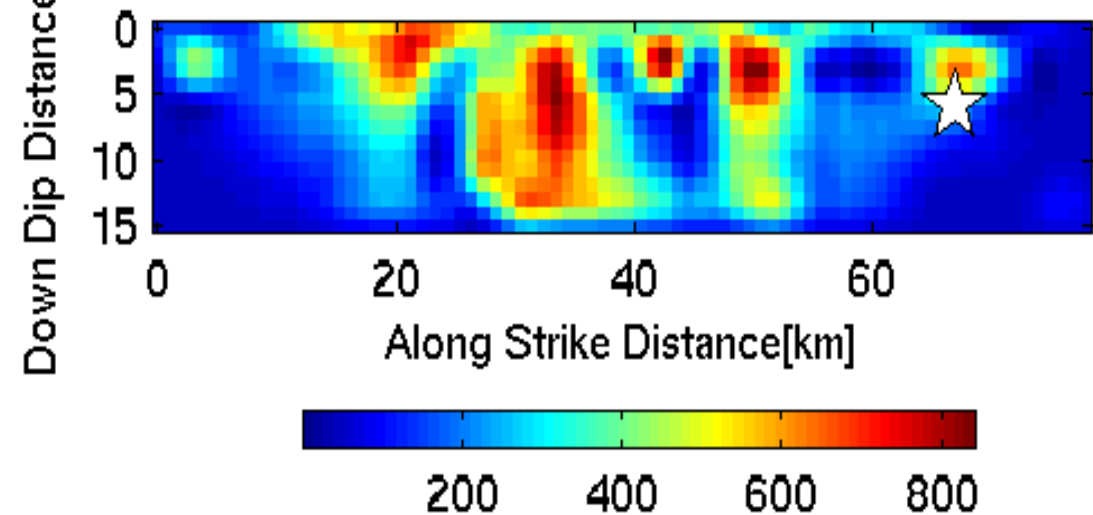
Landers (1992) - Cohee & Beroza, Mw = 7.17
[evID: 29.1; evNO: 38]



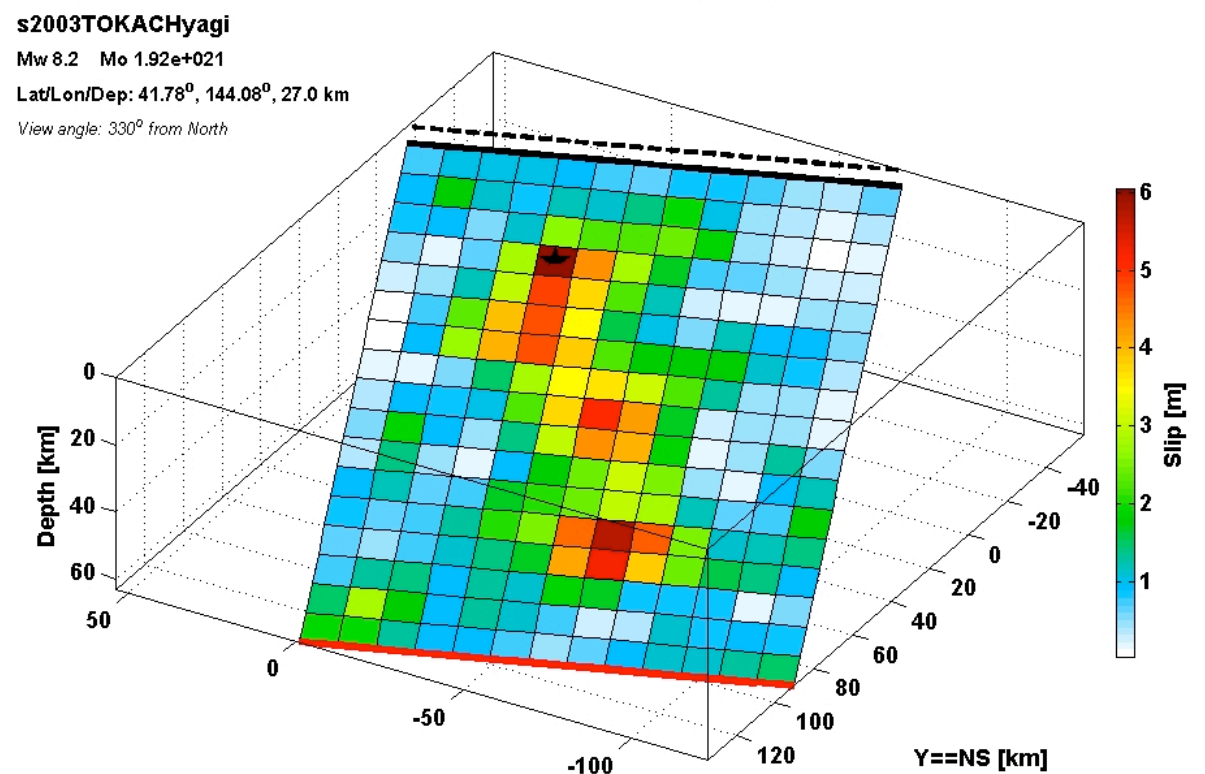
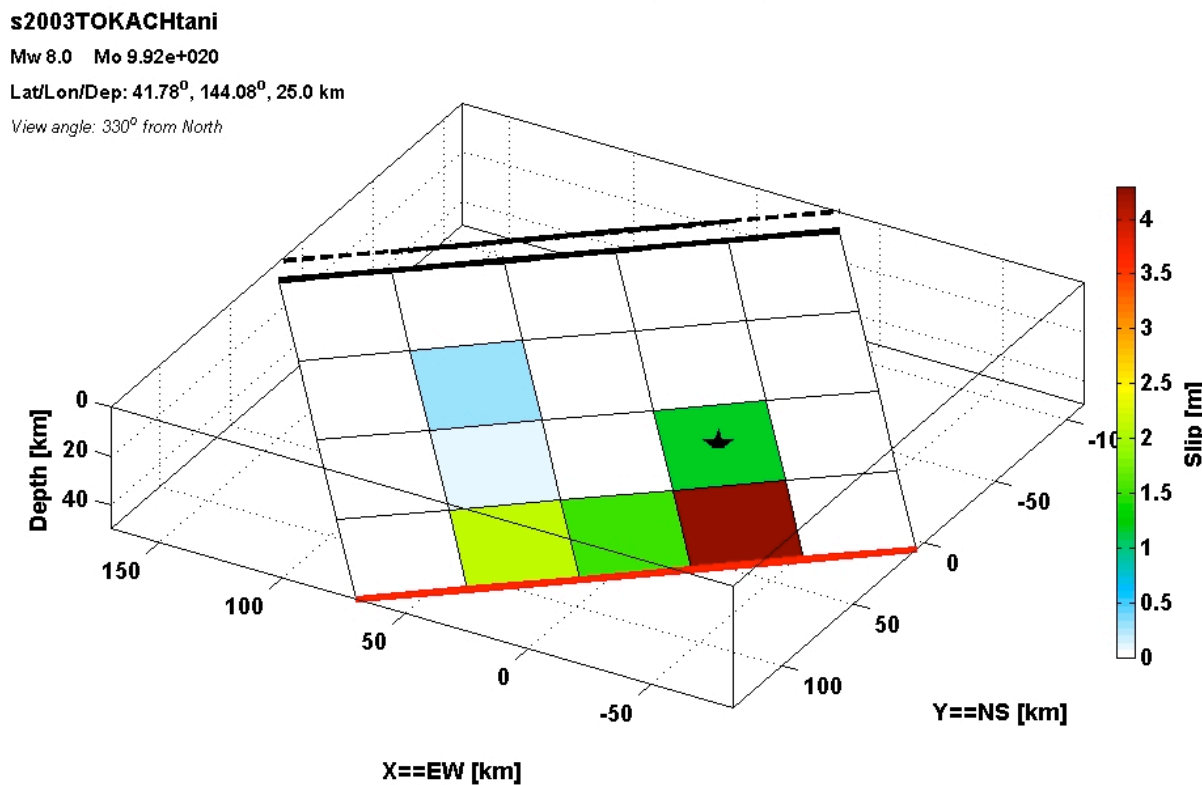
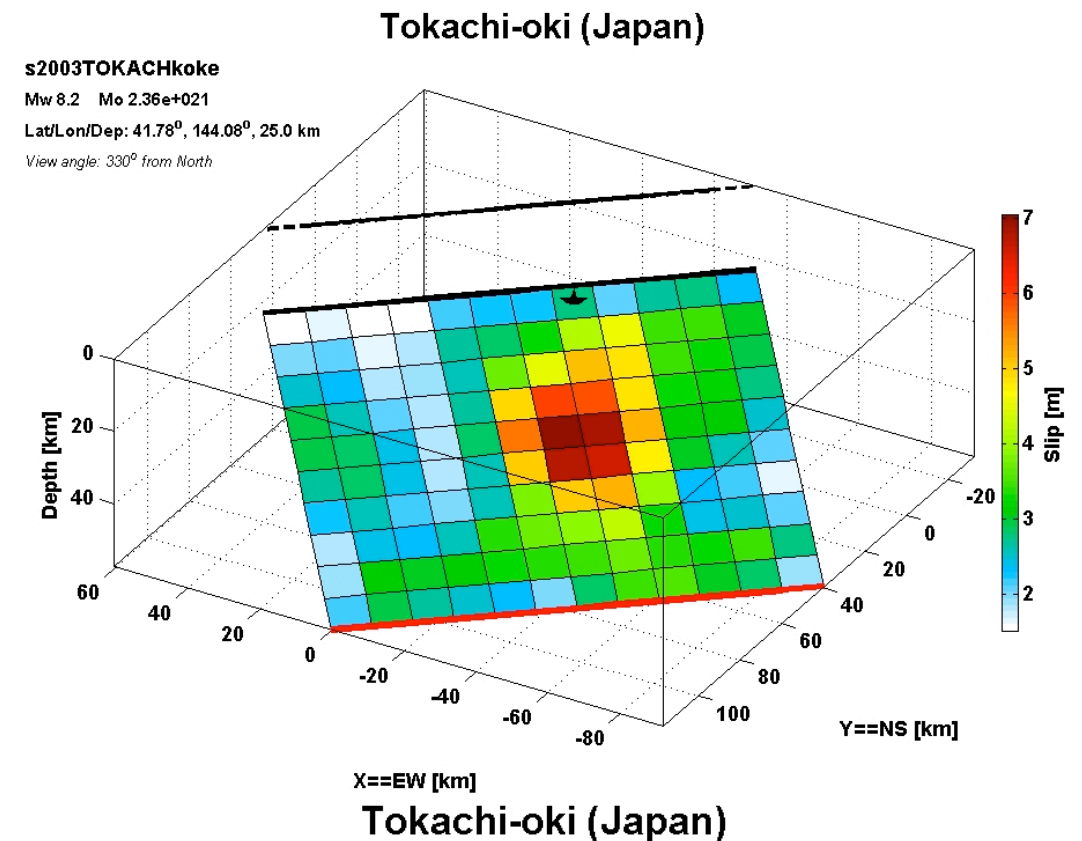
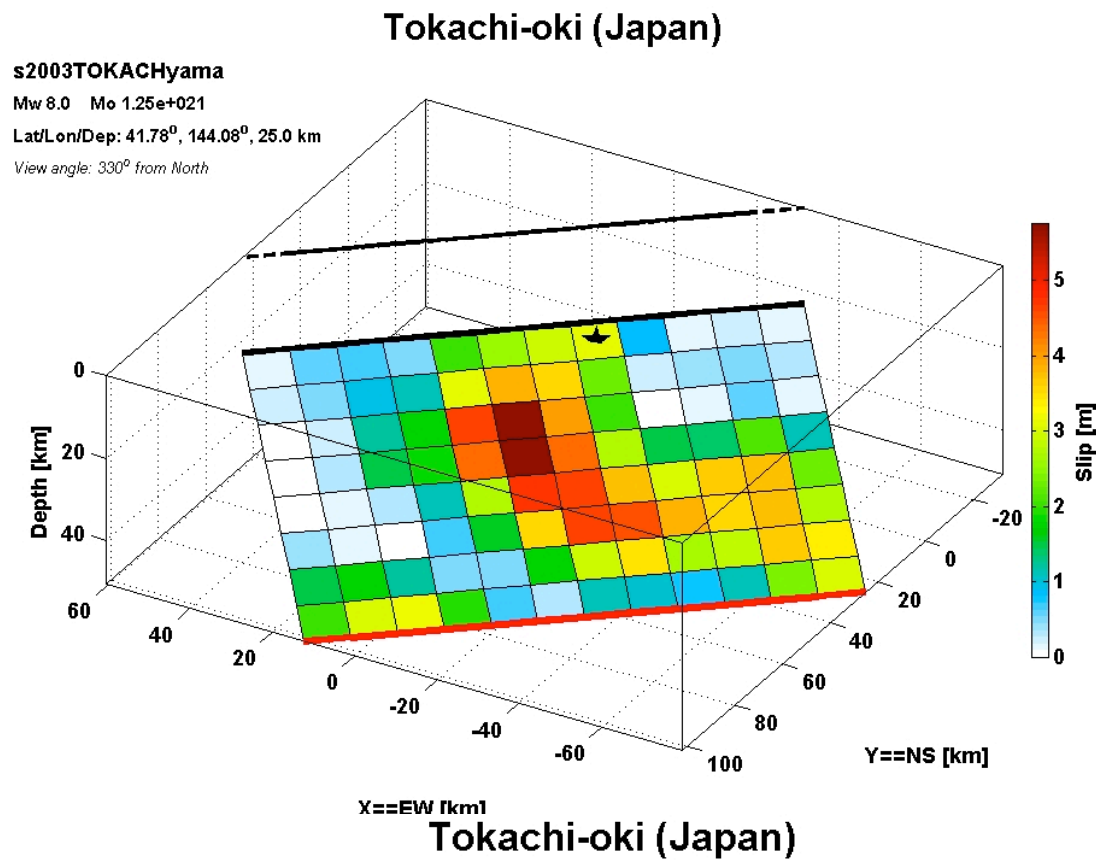
Landers (1992) - Cotton & Campillo, Mw = 7.26
[evID: 29.2; evNO: 39]



Landers (1992) - Wald & Heaton, Mw = 7.28
[evID: 29.4; evNO: 41]



Another example -- the Tokachi-oki earthquake

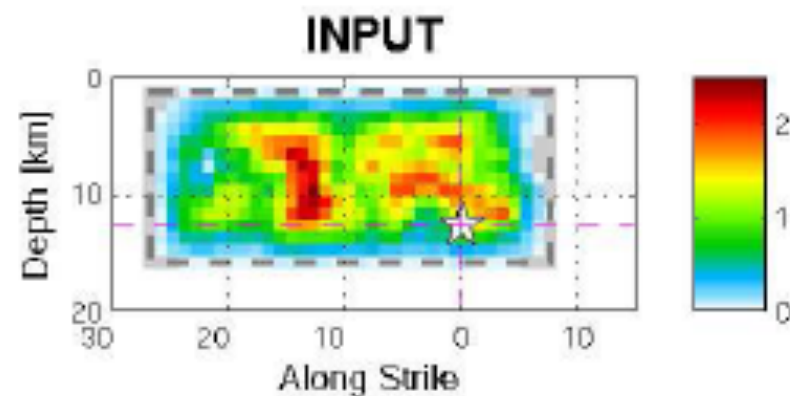


Questions about kinematic inversions

- What are the robust features of the models?
- How do the constraints and model parameterization affect the model result?
- Why do different inversions have such different slip models?
- How can we improve kinematic inversions to make the results more reliable?

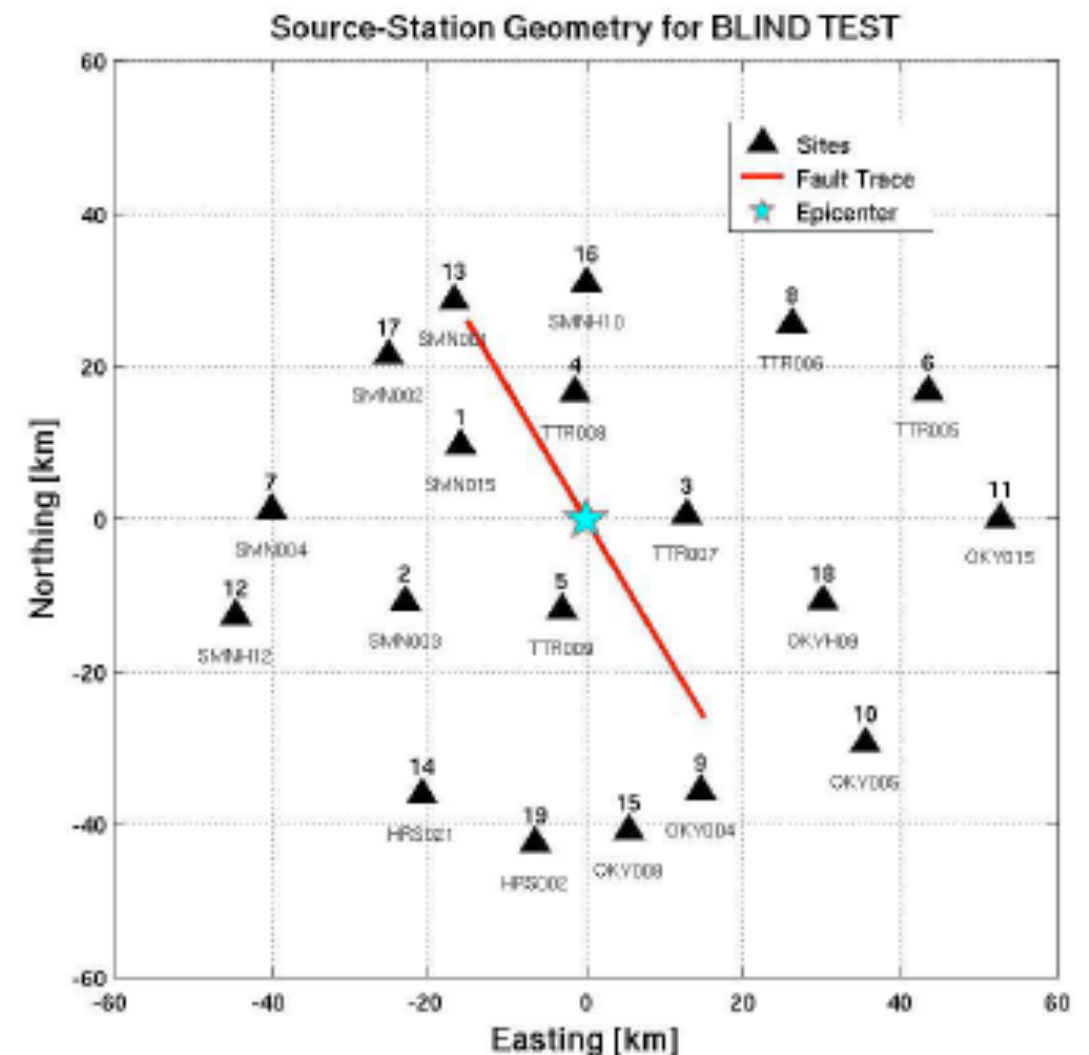
Martin Mai's SPICE Blind Test

Unknown to modelers, input model had a constant rise time, constant rupture velocity, and a triangular SVF



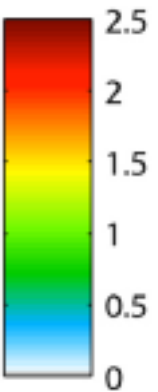
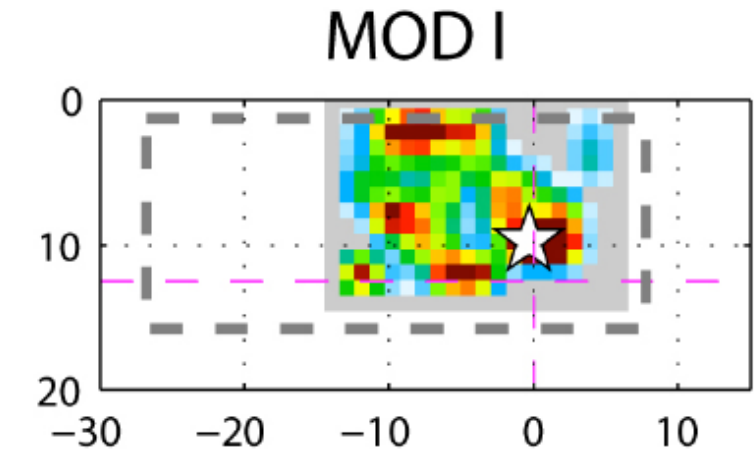
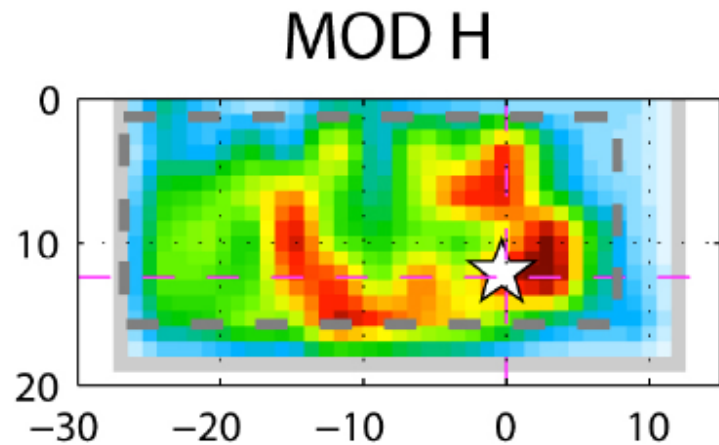
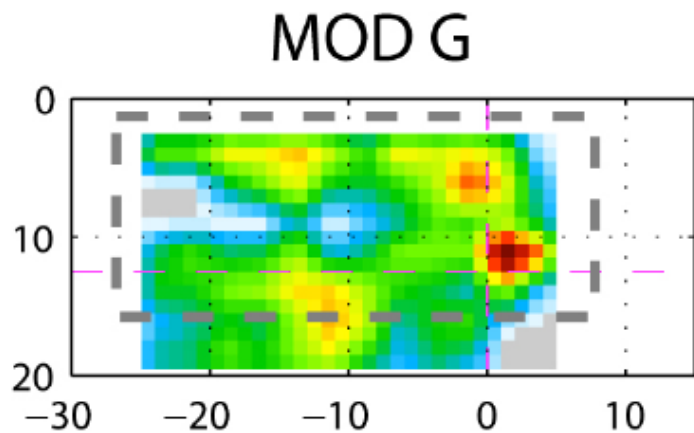
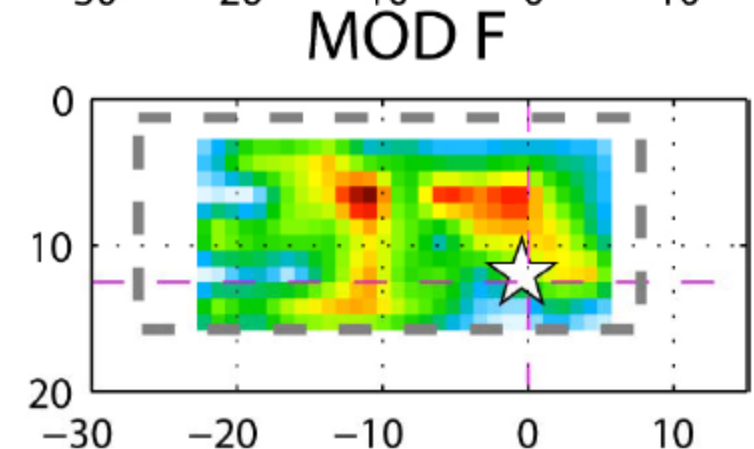
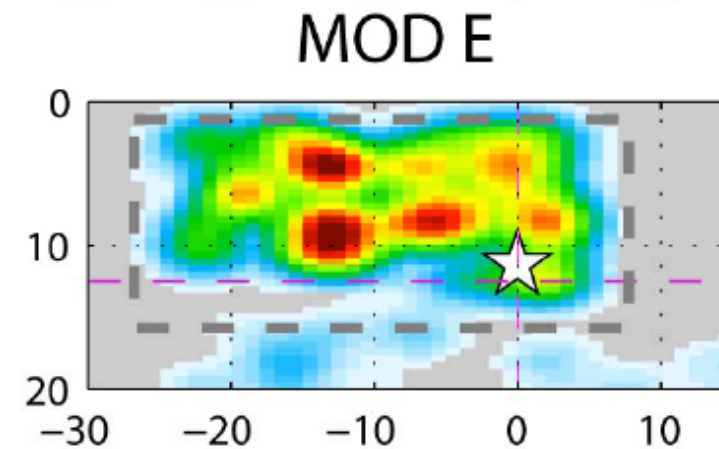
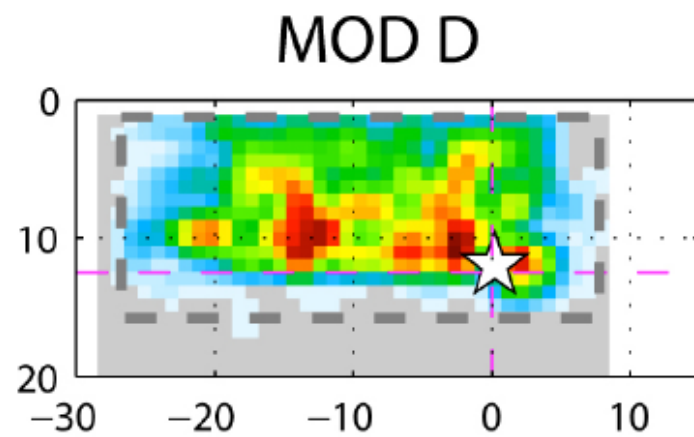
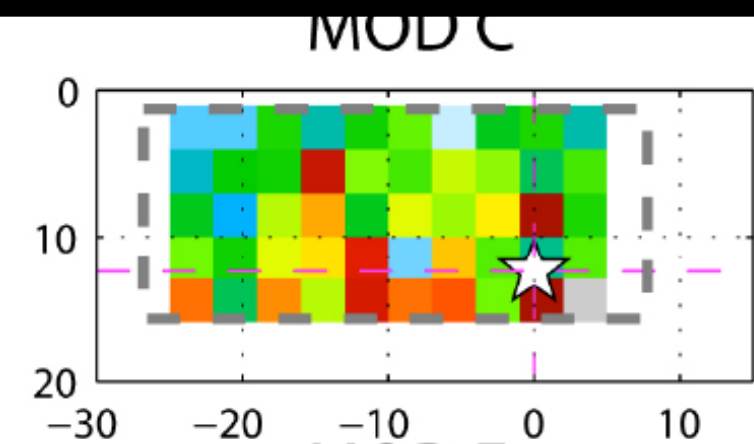
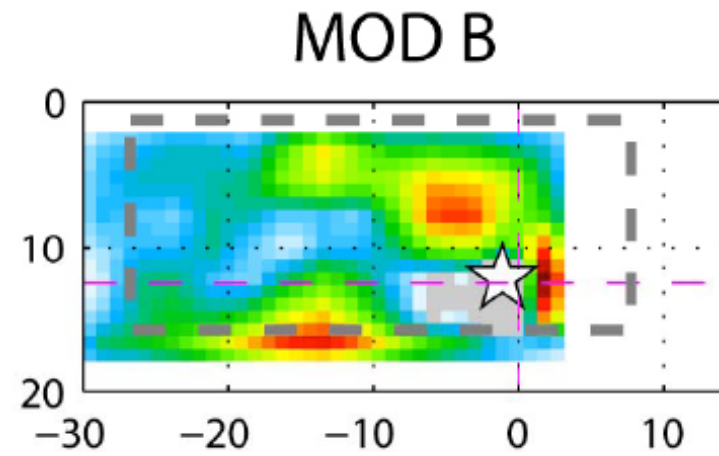
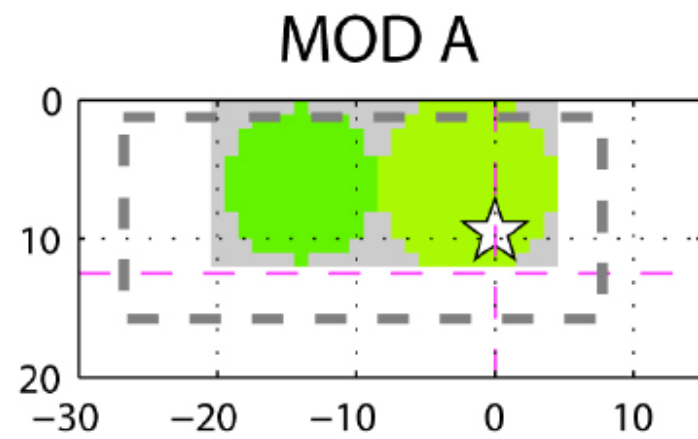
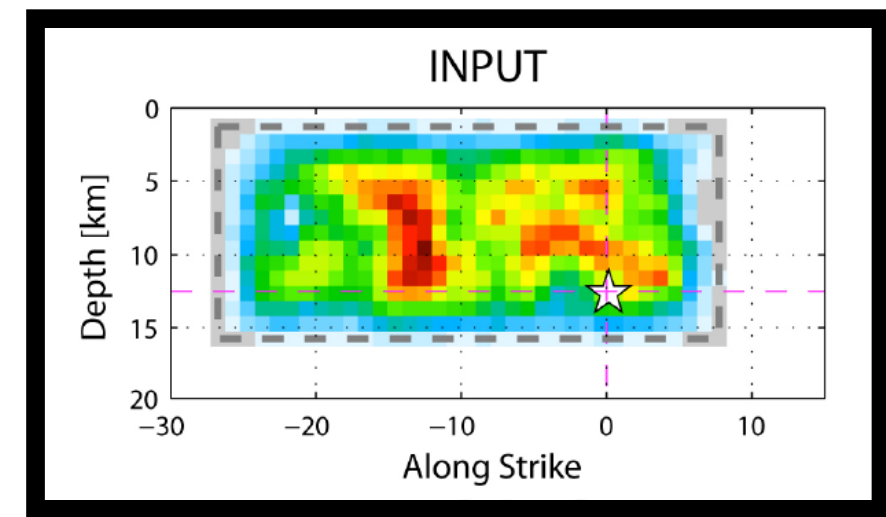
Modelers were given:

- seismic moment
- strike, dip, and rake
- hypocentral depth
- velocity-density structure
- noise-free synthetics

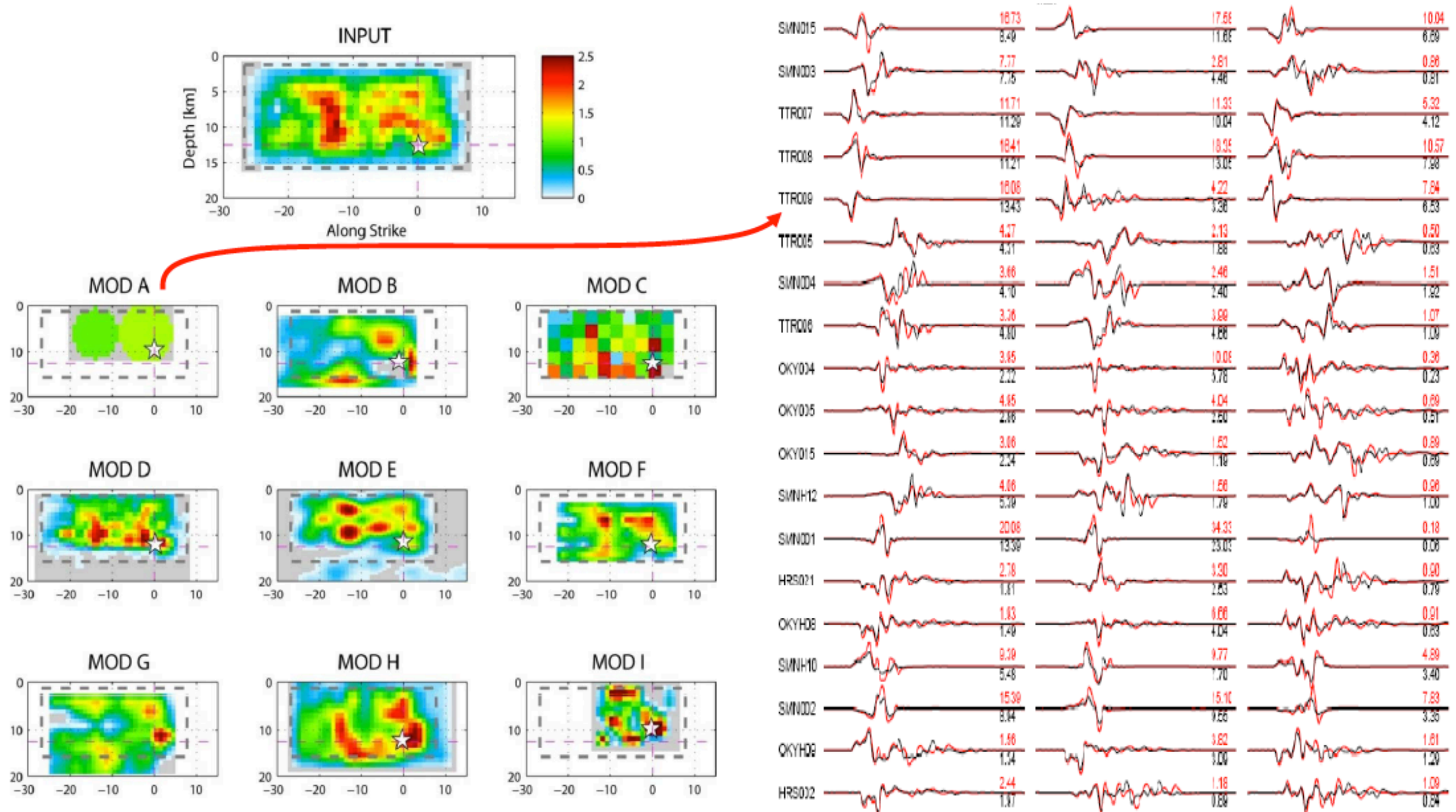


Mai, P. M., G. Festa, C. Francois-Holden, J. Burjanek, S. Di Carli, A. Emolo, A. Zollo, B. Delouis, and R. Madariaga, 2006.

Blind Test Results



Data fit \neq Model fit



Source Inversion Validation (SIV)

Martin Mai, Morgan Page, and Danijel Schorlemmer

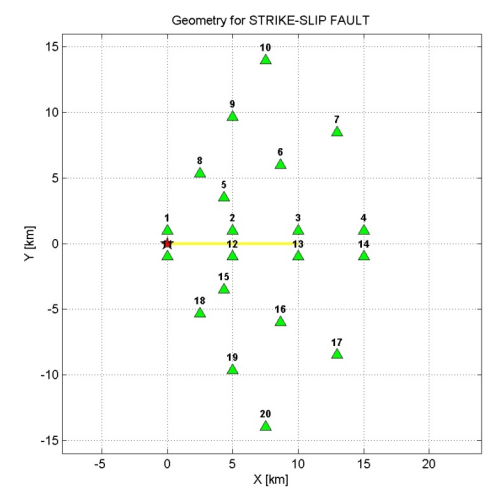
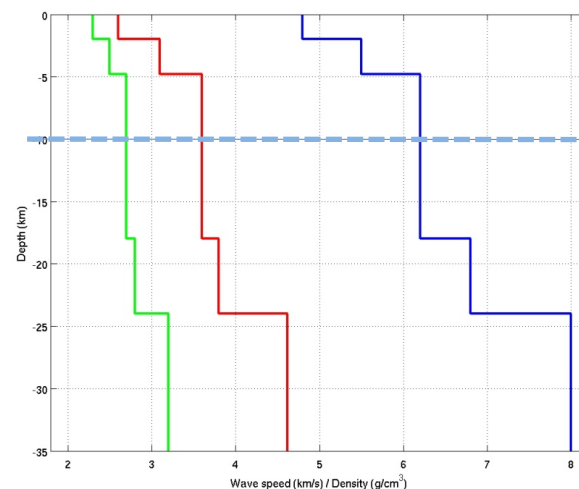
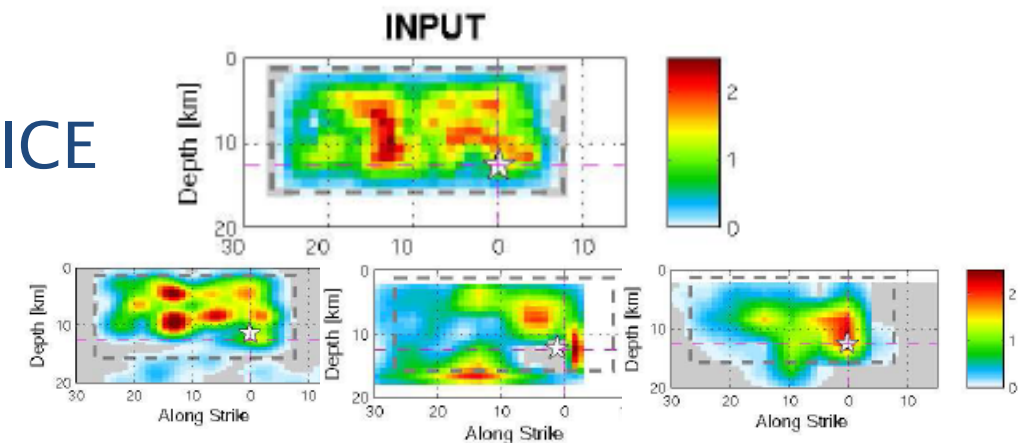
Previous Source Inversion Validation Exercise (SPICE Test) showed large variability between models

SIV Goals:

- Verify that the forward problem is being done correctly by all modelers
- Assess reliability, resolution, and robustness of different inversion strategies
- Develop testing center to host inversion “experiments” of varying complexity

First Steps:

- ❖ Problem 1a: Point-Source Green's function test)
- ❖ Problem 1b: Extended Source Green's function test)
- ❖ Problem 2: Simple Inversion



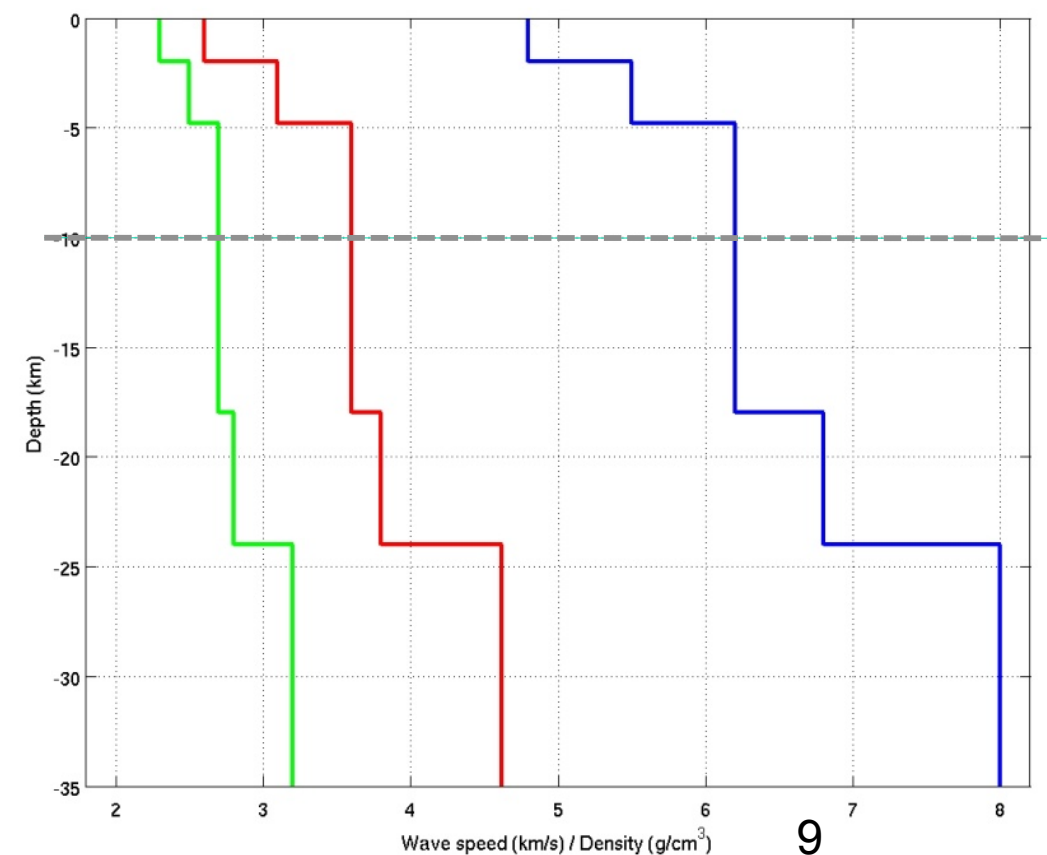
Source Inversion Validation

<http://siv.usc.edu>

Problem 1a: Green's Function Validation (point source)

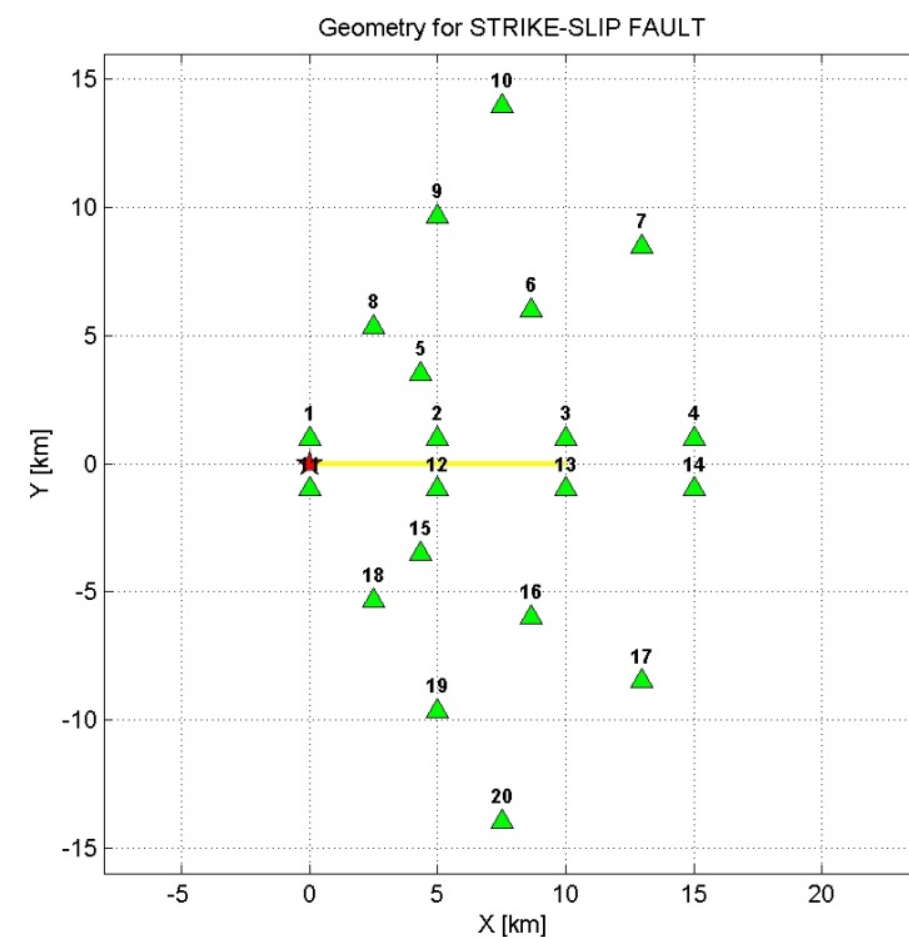
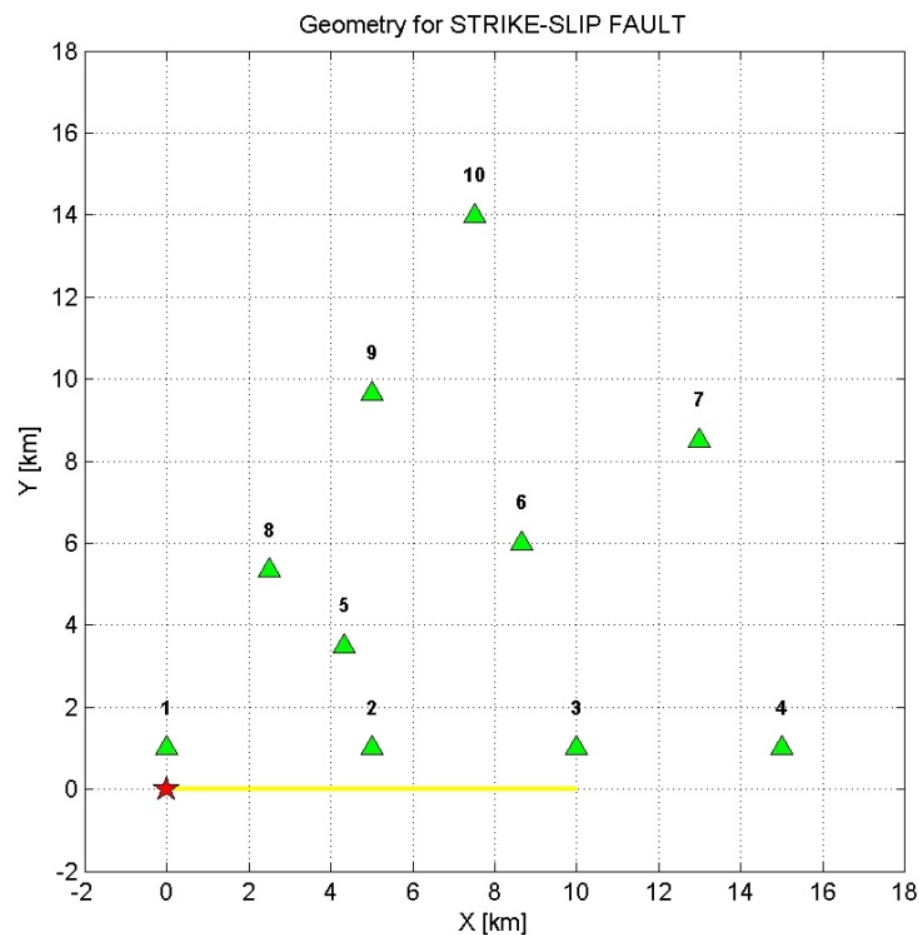
- During the 2008 SCEC workshop, it was questioned if all groups participating in the blind test calculated the Green's functions correctly
- The SIV-project thus starts with a test to verify GF-computations:
 - “point-source” at 10 km depth, parameterized as a 1 x 1 km² slip patch with homogeneous slip and boxcar slip-function of duration $t_r = 0.2$ sec
 - The shear-modulus at the given depth result in: M_w 4.992, $M_0 = 3.4992 \times 10^{16}$

Depth [km]	V_p [km/s]	V_s [km/s]	Density [g/cm ³]
0.0	4.8	2.6	2.3
-2.0	4.8	2.6	2.3
-2.0	5.5	3.1	2.5
-4.8	5.5	3.1	2.5
-4.8	6.2	3.6	2.7
-18.0	6.2	3.6	2.7
-18.0	6.8	3.8	2.8
-24.0	6.8	3.8	2.8
-24.0	8.0	4.62	3.2
-45.0	8.0	4.62	3.2



Problem 1a: Green's Function Validation (point source)

- Two cases are considered for the Green's function test
 - purely left-lateral strike-slip rupture on a vertical fault
 - purely thrust-motion on a 40° dipping fault
 - Stations at $Y = 1$ km parallel to surface projection of fault plane, and two arrays that are 30° and 60° rotated from the fault-parallel direction

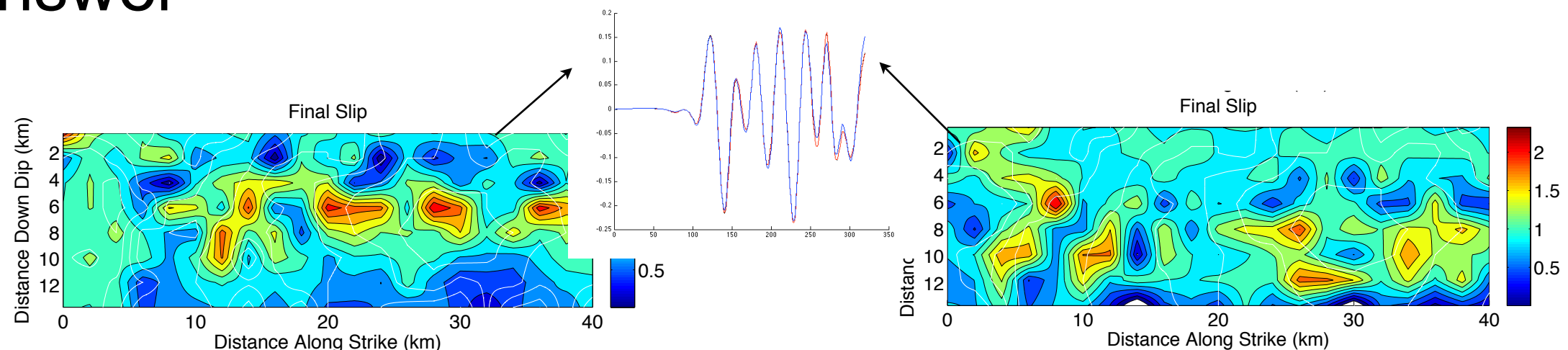


Differences between Dynamic Code Validation and Source Inversion Validation

- Must be blind (there is the possibility of tuning)

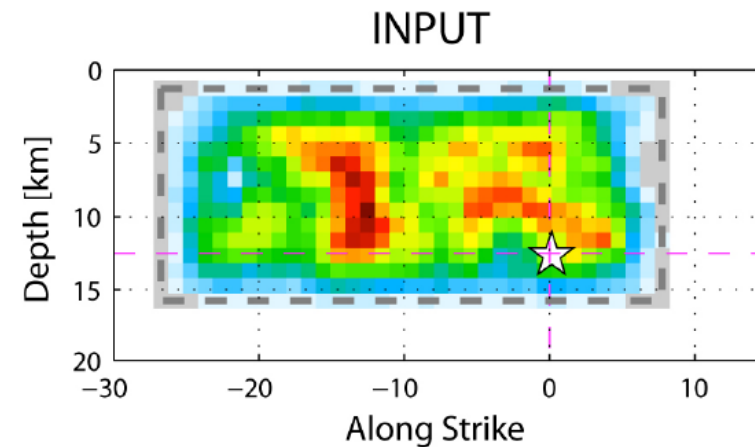
Amount of smoothing/regularization, geometry choices, data weights

- Nonuniqueness: there is more than one “correct” answer



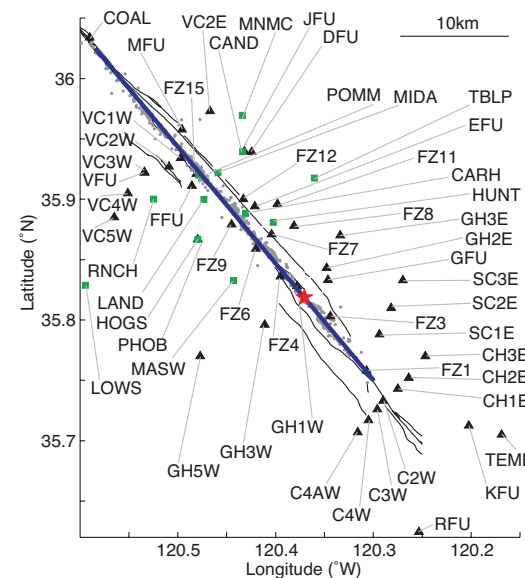
Types of Inversion Tests

- Kinematic Models (like original SPICE-test)



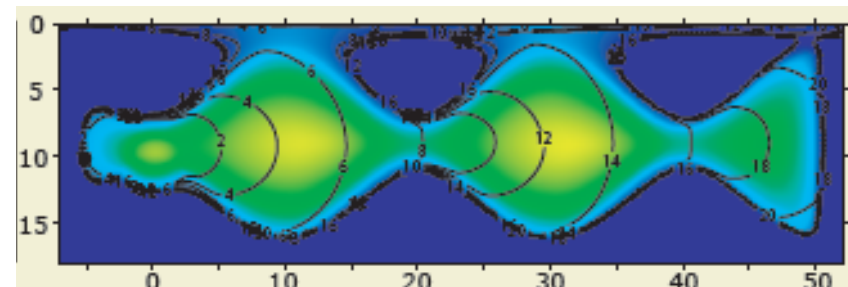
- Real Earthquakes

- construct earthquake from empirical Green's functions, or
- use subset of stations to produce synthetics at remaining stations



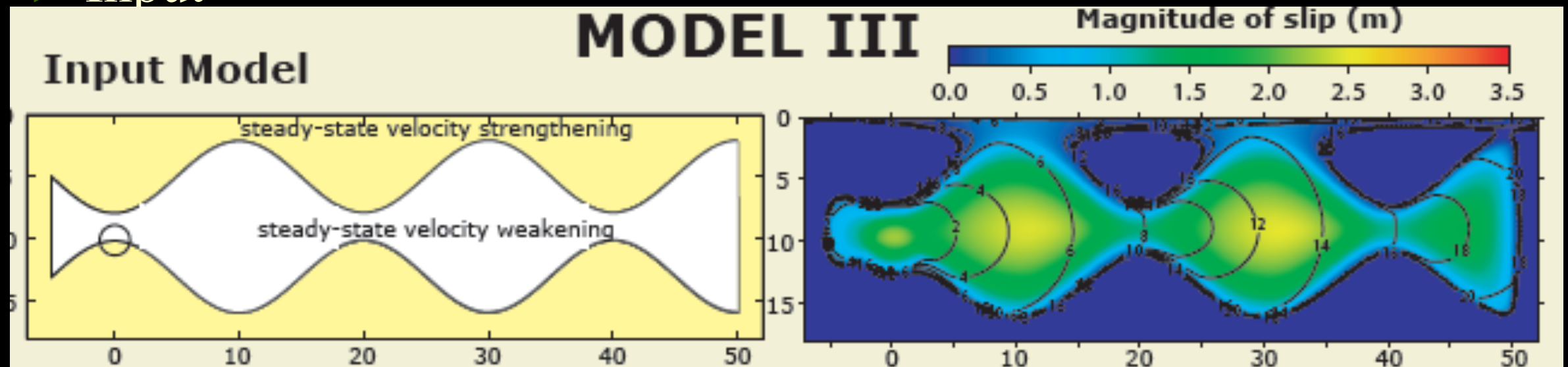
- Dynamic Models

- best of both worlds: can be realistic; true slip model is known

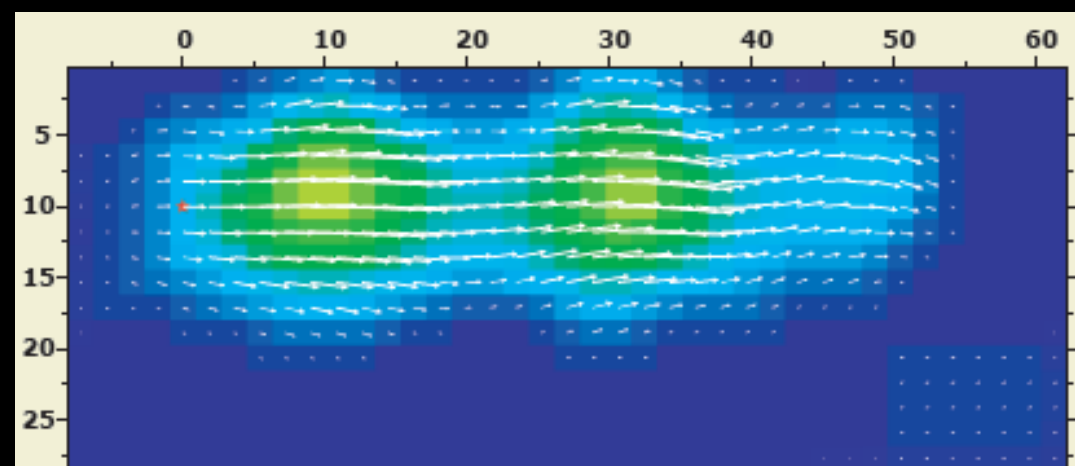


► Input

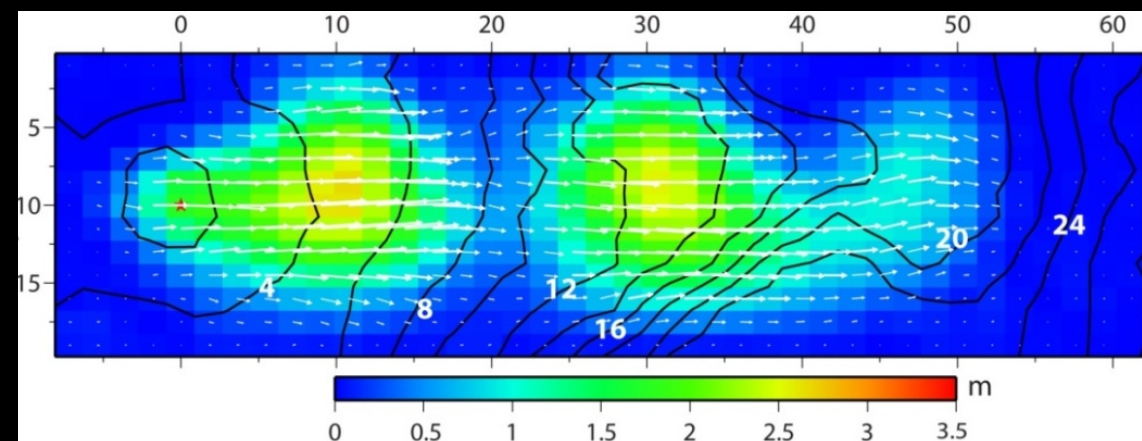
Model 3



GPS model

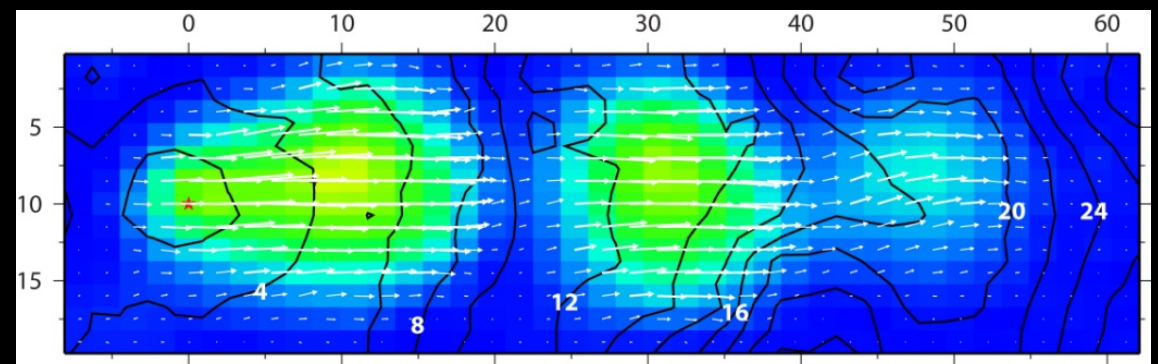


Joint: Symmetric Rise time

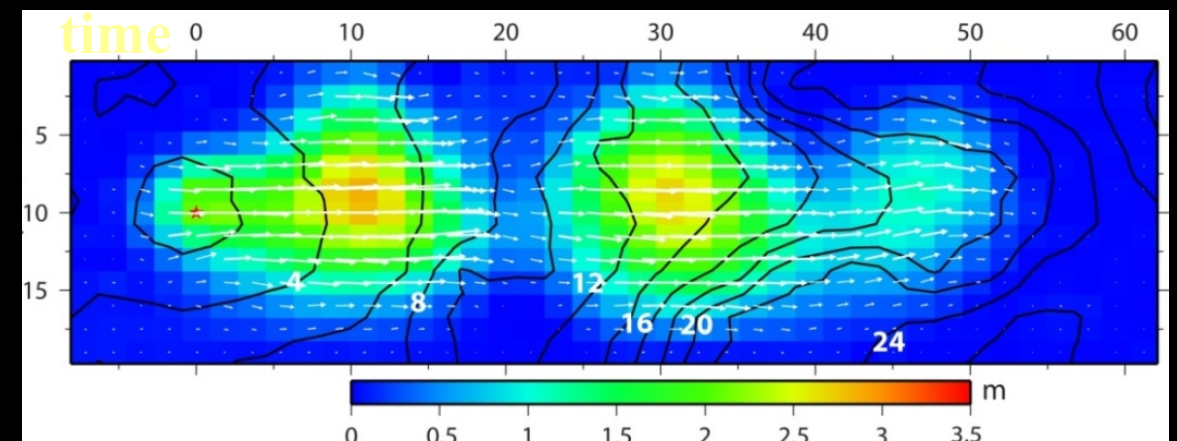


Inverted Kinematic Models

Seismic

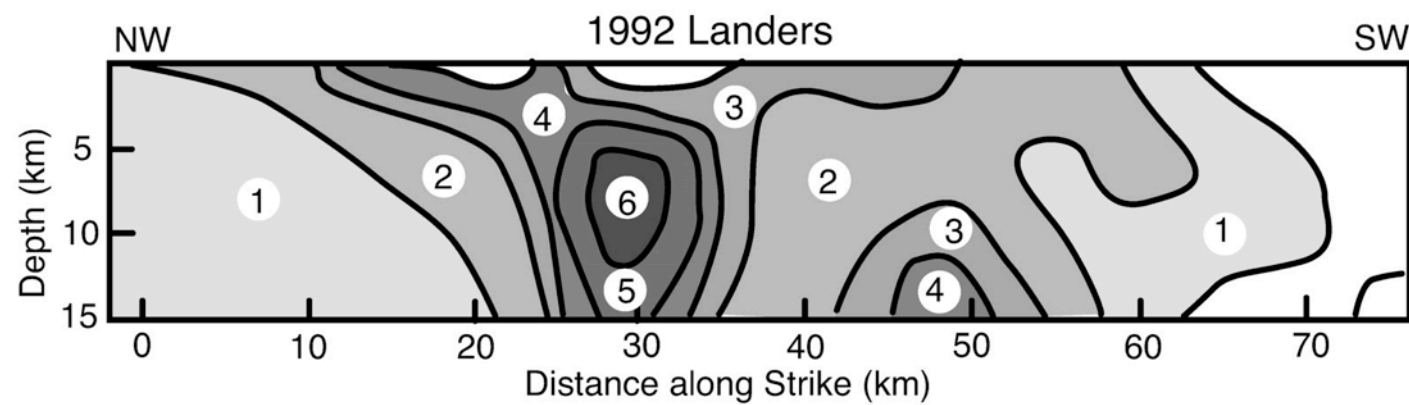
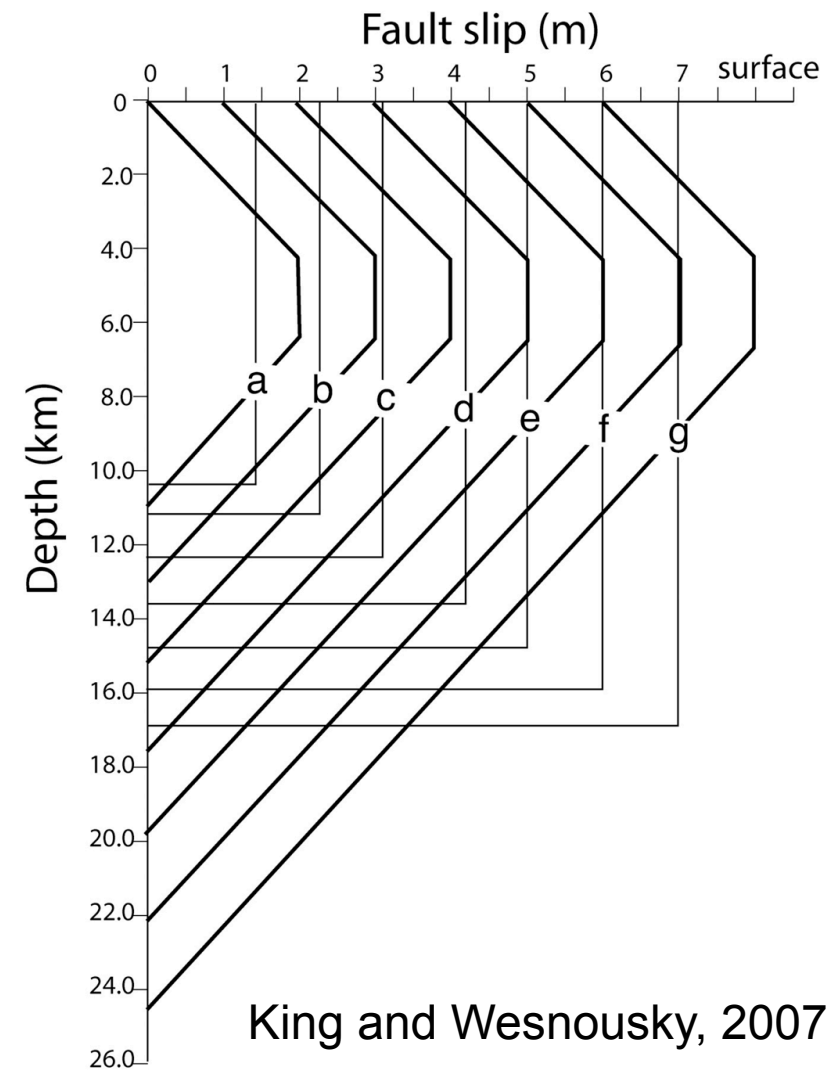


Joint: Asymmetric rise



Things we can test in SIV

● Can we resolve deep slip?



Wald and Heaton, 1994

Things we can test in SIV

- Can we resolve deep slip?
- Differentiate between crack-like and pulse-like ruptures?
- Resolvability of various parameters:
 - Slip distribution
 - Rupture speed (can we resolve supershear?)
 - Rise time

Things we can test in SIV

- Can we resolve deep slip?
- Differentiate between crack-like and pulse-like ruptures?
- Resolvability of various parameters

Lots of potential for collaboration
between dynamic modelers and SIV!

Source Inversion Validation

<http://siv.usc.edu>