



Introduction: Advancing Simulations of **S**equences of **E**arthquakes and **A**seismic **S**lip (**SEAS**)

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SCEC DR-SEAS Workshop, Apr. 23–24, 2018



Outline

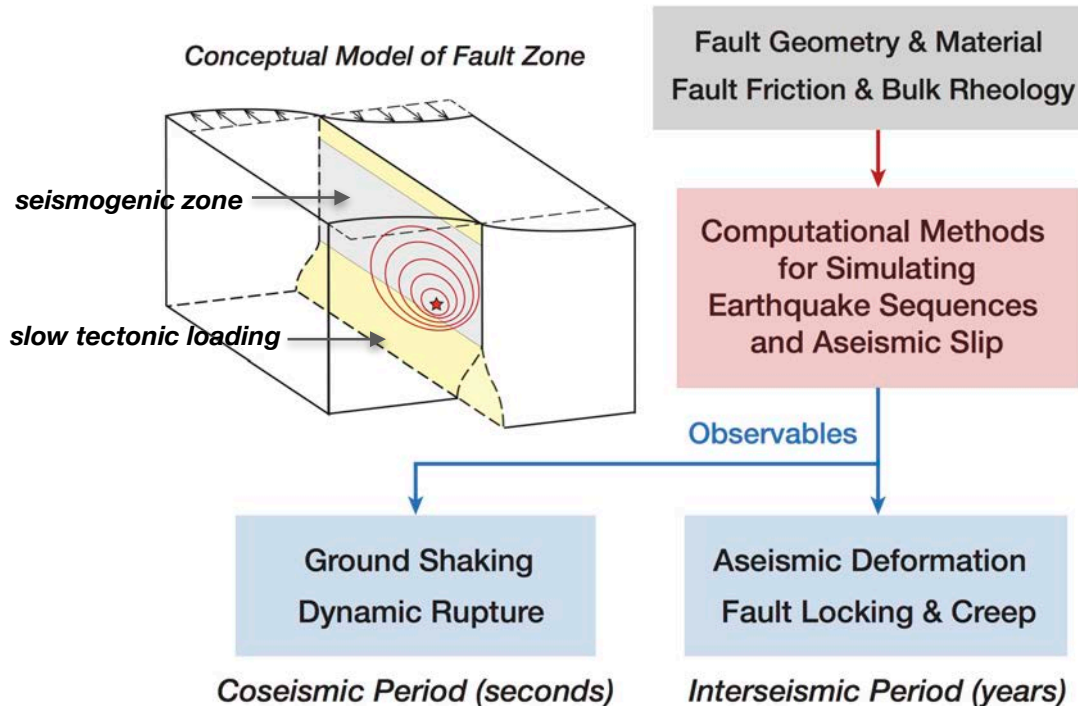
- Motivation
- Objectives
- Current activities
- Benchmarks for code verification
- Timeline for future activities
- Workshop agenda



Motivation

- **SEAS (aka “seismic cycle”) simulations** are now prevalent in earthquake research—addressing key SCEC objectives—but remain untested
- **Dynamic rupture (DR) group**
 - Simulating detailed single-event earthquake ruptures
 - Successful code **verification** exercises and ongoing **validation** efforts
 - **Imposed artificial prestress conditions and ad hoc nucleation procedures**
- **Earthquake Simulators (ES)**
 - Simulating millennium-scale seismicity patterns in fault systems
 - **Quasi-static approximation and some key physical features missing**
- **A new generation of verified SEAS models is needed**
 - Simulating longer periods of earthquake activity than single-event ruptures
 - Computational rigor and physically sound approaches

Ingredients & output of SEAS models

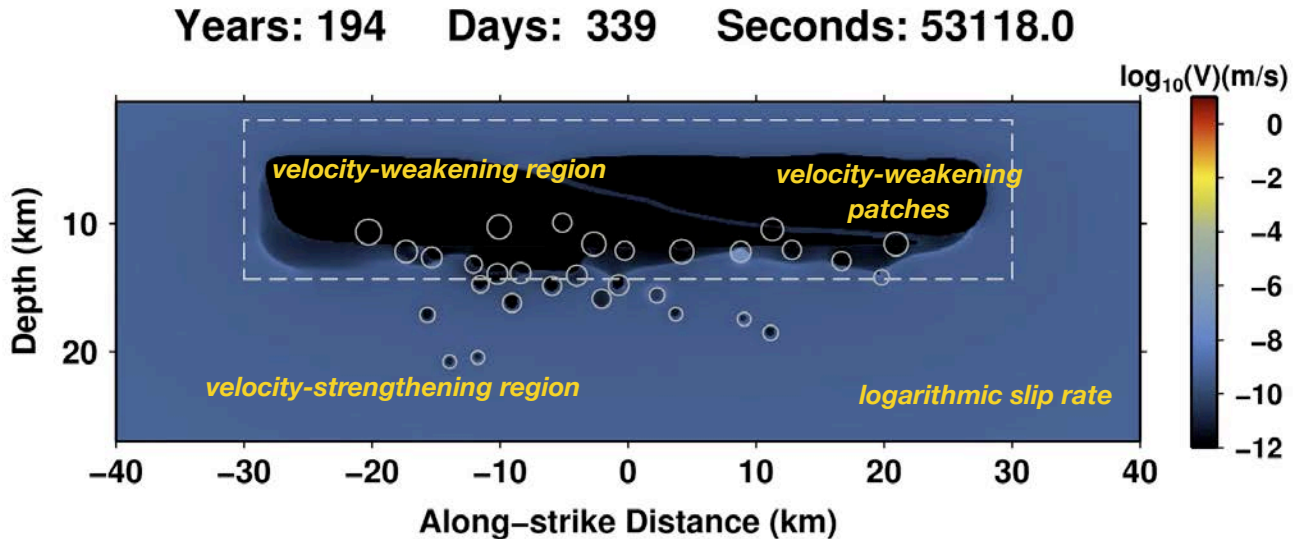




Problems that set SEAS models apart from DR

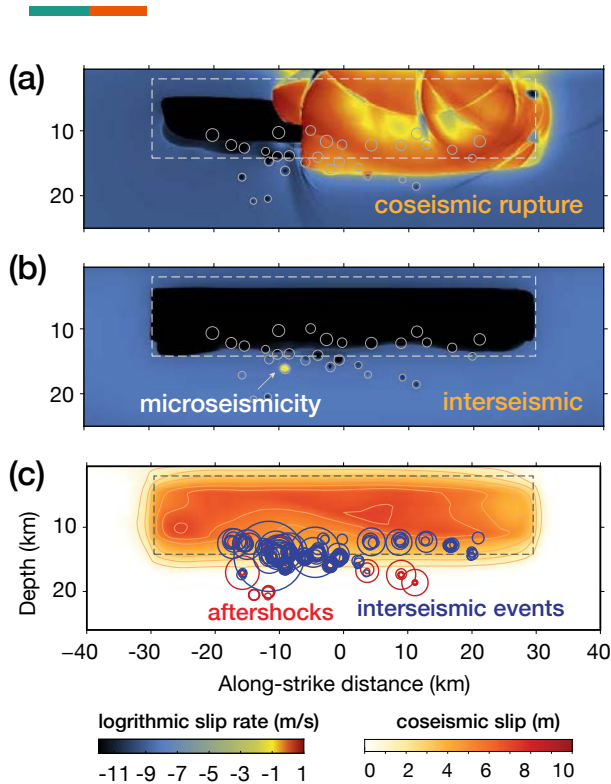
- The use of [variable time stepping](#) and possible switching between different computational schemes to capture inter- and co-seismic phases.
- The interaction between [nonlinear nature of the problem](#) and [accumulation of roundoff errors](#).
- The need to distinguish between [legitimate solution differences](#) and those due to improper choices of [algorithm, model resolution, and modeling procedures](#).
- The importance of [numerical efficiency and computational performance](#) for feasibility of even the most basic problems.

Examples of SEAS modeling



A planar fault in a 3D homogenous half-space

Jiang and Lapusta, Science, 2016



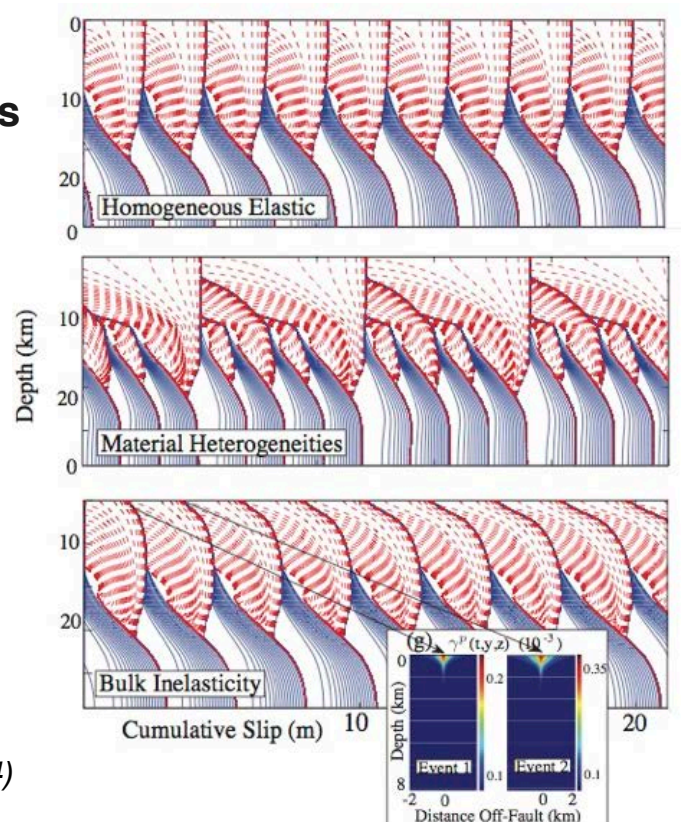
Complex interactions between earthquakes and aseismic slip

- Fully dynamic rupture
- Postseismic stress relaxation
- Microseismicity
- Complexity in large events
- Interseismic fault coupling
- Compare with seismological, geodetic, and geological data

How rheology and structure influence earthquake sequences

- Quasi-dynamic earthquake ruptures in 2D antiplane models
- Heterogeneous bulk material properties
- Off-fault plasticity

cumulative fault slip along depth



Erickson and Dunham (JGR, 2014)
Erickson et al. (JMPS, 2017)



Complexities in SEAS problems

- Transition from **slow, quasi-static** to **dynamic, wave-producing** slip
- Stress transfer due to **dynamic waves**
- Transition to **postseismic** slip
- **Postseismic** and **interseismic** slip and the associated stress redistribution
- Interaction with the **deep visco-elasto-plastic response** and the associated stress redistribution
- Interaction with **fluids** throughout the cycle
- Interaction with **off-fault damage and healing**
- The role of geometrical complexities

Investigated in a number of studies (*e.g.*, Jiang and Lapusta, 2016; Erickson and Dunham, 2014; Luo and Ampuero, 2011; Barbot et al., 2012; Liu, 2013; Wei, 2013; Segall and Bradley, 2012; Kaneko et al., 2011; van Dinter et al., 2013; Hajarolasvadi and Elbanna, 2017; Kroll et al., 2017; Tal et al., 2018)



Some outstanding questions

- How do these physical factors influence the earthquake cycle? Do they matter? How to implement them with efficiency in 3D, larger scale simulations (e.g., Earthquake Simulators at SCEC)?
- Do our numerical models resolve the “true” fault behavior and its complexity? What features in models may arise from numerical approximation and resolution issues?
- What are the best practices and significant issues for SEAS modeling?



Objectives of SEAS working group

- Lead the efforts on code verification of SEAS models
- Explore important issues in SEAS modeling and further advance our computational capabilities
- Promote robust and reproducible earthquake science
- Lend experience and tools to the community
- Provide synergy with other SCEC working groups such as the Dynamic Rupture group, Earthquake Simulators, Community Rheology Model, etc



Past & current activities

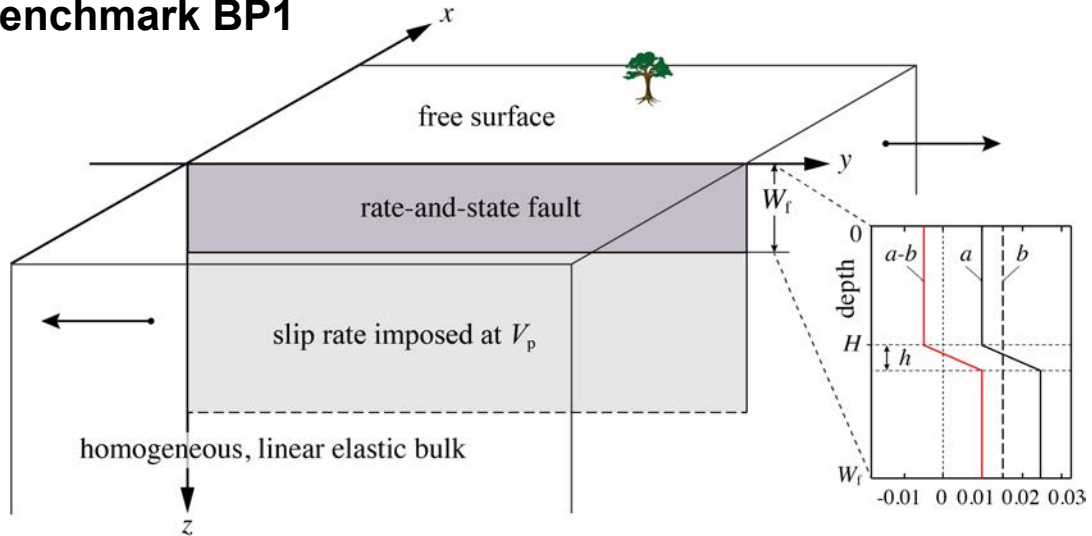
- Submitted SCEC proposals for working group and workshop (Nov.)
- Developed the first Benchmark Problem BP1 (Mar.)
- Established online platform with basic model comparison tools (Mar.)
- Received and analyzed 23 submissions from 11 modelers
- The current workshop for science talks, benchmark results, & discussions



Benchmarks for code verification

- Guidelines
 - Start simple & incrementally increase model complexity
 - Take advantage of experience and tools from the dynamic rupture group
 - Design benchmarks that maximize participations
 - Develop the web platform based on comparison needs
- Tasks
 - What model features should we compare?
 - How do we assess agreements and discrepancies?
 - What constitute successful code verifications for SEAS models?

1st benchmark BP1



2D anti-plane shear motion. The fault is a vertical strike-slip fault in a homogeneous half-space. Friction is regularized rate-and-state friction with the aging law. (readily adaptable to a 3D benchmark)

Online platform

- Code verification web server installed and maintained by Michael Barall (<http://scecddata.usc.edu/cvws/seas/index.html>)
- Using existing architecture/tools from dynamic rupture group



The SCEC Sequences of Earthquakes and Aseismic Slip Project

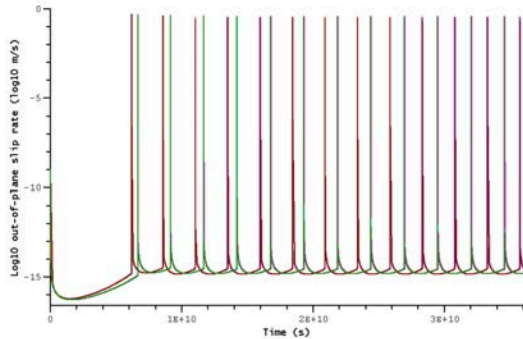
[Benchmark Comparison Tool](#)

[Benchmark Descriptions](#)

[Downloads](#)

Benchmark results

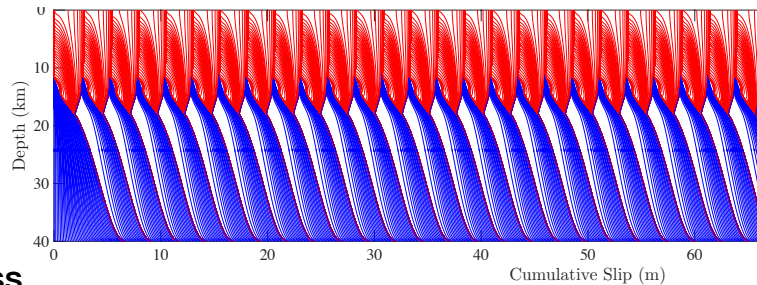
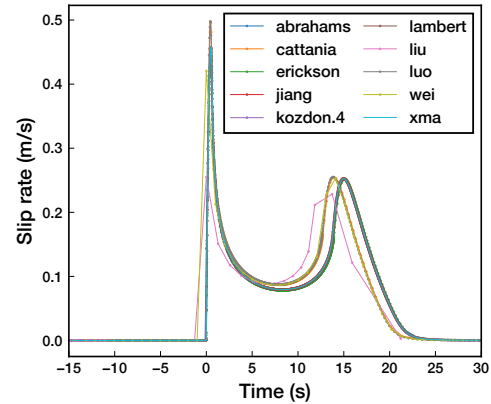
11 models and 23 model submissions



- abrahams (100 km X 80 km: Free surface outer BC)
- barbot.2 (Sylvain Barbot (Matlab))
- cattania (Camilla Cattania - fdra (bem))
- erickson (Brittany Erickson)
- jiang (Junle Jiang (25 m; 80 km))
- kozdon.4 (SIPG :: 160 km X 80 km :: free surface outer BC)
- lambert (Valère Lambert - 25 m, 80 km domain)
- Liu.2 (Yafeng Liu)
- Luo (ODIN - Yingdi Luo, Ben Idini and Pablo Ampuero)
- wei (Matt Wei)
- xma (MSC-Cycle_25m_80)

long-term evolution of slip/rate/stress
(online platform)

coseismic processes (manual)



Slip evolution along depth (manual)



Benchmark design

- Ingredients in benchmark design
 - 2D anti-plane/in-plane or 3D problems
 - State evolution in friction laws (aging vs. slip formulations)
 - Complexity in structure, geometry, or frictional properties
 - Fluid processes, inelastic effects, etc.
- The next benchmark(s)
 - 3D problem similar to BP1 (with a lower resolution)
 - 2D problem with viscoelasticity
 - 2D problem with different evolution laws
- Future benchmarks?



Timelines for future activities

- Proposals for 2018
 - SEAS verification exercises in SCEC5: Pending
 - Co-PIs: Erickson, Jiang, and Barall
 - Other modelers to request separate funding from SCEC or others
 - One-day SEAS-themed workshop (2019 Spring): Pending
- Conference presentations
 - 2018 SCEC and AGU annual meetings, and others.
- Group meetings
 - 2018 SCEC meeting and potential 2019 workshop
- Publications
 - Development of an initial set of 2D/3D benchmarks and significant SEAS issues



Workshop agenda

Monday afternoon:

SEAS modeling and its connections to dynamic rupture problems

| | | |
|---------------|--|--|
| 14:30 - 15:00 | Introduction to SEAS activities | <i>Brittany Erickson / Junle Jiang</i> |
| 15:00 - 15:15 | SEAS: on resolution, complexity, and dynamic effects | <i>Nadia Lapusta</i> |
| 15:15 - 15:30 | Modeling of the nucleation process of laboratory and crustal earthquakes | <i>Yoshihiro Kaneko</i> |
| 15:30 - 15:45 | Coupling spectral boundary integral and volume-based models for high resolution fault zone physics | <i>Ahmed Elbanna</i> |
| 15:45 - 16:00 | Modeling the rupture process on rough faults during multiple slip events with the mortar finite element method | <i>Yuval Tal</i> |
| 16:00 - 16:15 | <i>Break</i> | |
| 16:15 - 16:30 | Discontinuous Galerkin methods for earthquake cycle simulations | <i>Jeremy Kozdon</i> |
| 16:30 - 16:45 | RSQSim modeling and applications | <i>Kayla Kroll</i> |
| 16:45 - 17:30 | Discussions | |



Tuesday morning:

Multi-physics and diverse observables in SEAS models

| | | |
|---------------|--|--|
| 08:30 - 08:45 | The effect of shear heating on the earthquake cycle | <i>Kali Allison</i> |
| 08:45 - 09:00 | Time stepping for earthquake cycles with plasticity | <i>Brittany Erickson</i> |
| 09:00 - 09:15 | Modelling frictional faults as plastic shear bands in nonlinear media | <i>Casper Pranger</i> |
| 09:15 - 09:30 | FDRA - Fault dynamics with radiation damping approximation: history and capabilities | <i>Paul Segall</i> |
| 09:30 - 09:45 | The spectrum of rupture styles at subduction zone governed by the geometry and rheology of the upper plate | <i>Sylvain Barbot</i> |
| 09:45 - 10:00 | Modeling of slow slip events on a non-planar subduction fault | <i>Yajing Liu</i> |
| 10:00 - 10:15 | Numerical simulation of dynamic triggering of slow slip events in California and New Zealand | <i>Matt Wei</i> |
| 10:15 - 10:30 | Break | |
| 10:30 - 12:00 | Benchmark results and discussions | <i>Brittany Erickson / Junle Jiang</i> |
| 12:00 - 13:00 | Lunch | |
| 13:00 - 14:30 | Workshop wrap-up and future plans | <i>Brittany Erickson / Junle Jiang</i> |